

Applying BCO Algorithm to Solve the Optimal DG Placement and Sizing Problem

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Abstract In this paper, the problem of DG placement and sizing for loss reduction and line capacity improvement has been considered and evaluated. In order to solve the optimization problem, authors are using the novel and heuristic BCO algorithm. This algorithm is inspired of the intelligent behaviour of bees during the nectar search process. Finally, the results of applying the Bee Colony Optimization algorithm for DG placement and sizing in IEEE 33 nodes test network are shown.

Keywords Bee Colony Optimization, Placement, Distributed Generation, Loss Reduction, Line Capacity Improvement

1. Introduction

According to the continuous growth of restructuring in distribution system, the issue of using distributed generation resources (DGs)– due to advantages such as distribution loss reduction, line capacity and voltage profile improvement, increasing the reliability, environmentally friendly and etc.–has been considered severely. But despite the afore mentioned benefits, the incorrect selection of location, number and/or capacity of DG lead to rise of network problems. Therefore, to reach optimal operation of distribution network, optimal DG placement and sizing is essential [1-4], [30]. To meet this goal, the parameters such as losses, line capacity, voltage profile and reliability should be evaluated in all states before and after the DG installation, and the best solution should be selected. But due to the complexity and time consuming, authors are using the bee colony optimization algorithm inspired by bees' intelligent behaviour in nature for nectar search, to solve this problem. According to high importance degree of losses in Iran (more than 20%) the loss and line capacity indexes will be considered.

1.1. Literature Review

With the daily growth of using DGs in distributed networks, optimal positioning of these resources by considering different objectives such as loss reduction, the voltage profile improvement, etc. has been solved by different methods such as GA, PSO, CPSO, ACO, etc.

A summary of carried out activities in this field can be seen in table 1.

Some of the innovations discussed in this Paper are solving the problem by the BCO novel method, reaching very

high flexibility in produced program, and determination of the DG capacity floatingly.

2. Introducing the Indexes for DG Placement and Determining the Objective Function

2.1. Loss Reduction Index

In terms of heavy loads, transmission and distribution lines have a double significance because in such a condition a penalty as energy with higher price or disadvantage will be inflicted to the consumer or distribution company, respectively. These losses are caused by power transmission through the lines with resistance. Therefore by means of DGs, we can reduce the amount of transmitted power and in this way the losses will be reduced consequently. [1-4, 26, 32-33]

The loss in distribution network is calculated by the following formula:

$$P_{Loss} = \sum_{i,j=1}^n (R_{ij} \cdot real(I_{ij})^2) \quad (1)$$

Where: P_{Loss} stands for the total losses in distributed network, R_{ij} for the resistance of the line between bus i and bus j , I_{ij} for the amount of current in line ij , and n shows the number of buses.

In evaluating this index, we should consider the following constraints: [1-4]

Power balance

$$P_{Network} + \sum P_{DG} = \sum P_{demand} + P_{Loss} \quad (2)$$

Where: $P_{Network}$ stand for the power entered to the network from main supply and P_{DG} shows the DG capacity.

Range of network losses

$$P_{Loss}(WithDG) \leq P_{Loss}(WithoutDG) \quad (3)$$

Range of active and reactive power production with DGs

$$P_{DG_i}^{min} \leq P_{DG_i} \leq P_{DG_i}^{max} \quad (4)$$

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$$Q_{DG_i}^{min} \leq Q_{DG_i} \leq Q_{DG_i}^{max} \quad (5)$$

Line's thermal limit

$$|I_{ij}| \leq |I_{ij}|^{max} \quad (6)$$

2.2. Index of Line's Free Capacity

Another benefit of using DG is to reduce the transmitted power through lines. This increases the free capacity of lines and therefore prevents from establishment of new lines, substations and etc.[1-4, 26-33]

With calculating the current flows through the lines, before and after the installation of DGs and comparing the network flow in these two states, another component of the objective function will be built.

$$IC_0 = \sum |I_{ij}|_{\text{WithoutDG}} \quad (7)$$

Where: IC_0 is total transmitted current in the network before DG installation.

$$IC = \sum |I_{ij}|_{\text{WithDG}} \quad (8)$$

Where: IC is total transmitted current in the network after DG installation.

$$F_{IC} = \frac{IC}{IC_0} \quad (9)$$

2.3. Determination of the Objective Functions

By considering both indexes, loss reduction and increasing the free capacity of the lines, the objective function will be considered as follow:

$$\text{CostFunction} = w_1 \times F_{IC} + w_2 F_{Loss} \quad (10)$$

Where:

$$F_{Loss} = \frac{P_{Loss}}{P_{Loss0}} \quad (11)$$

And w_1 and w_2 are objectives weight.

Also the following two equations help us to the better understanding of the impact of DG installation on the network:

$$F_I = 1 - F_{IC} \quad (12)$$

$$F_L = 1 - F_{Loss} \quad (13)$$

2.4. DG Modelling

Generally the operational DG models in distribution networks are divided into two categories:

PV model

PQ model

In this paper, authors assume that, all DGs are modelled as PQ.[2, 4]

3. Bee Colony Optimization Algorithm (BCO)

Social insects (bees, wasps, ants, termites) have been living on the Earth for millions of years, building nests and more complex dwellings, organizing production and procuring food. The colonies of social insects are very flexible and can adapt well to the environment changes. This flexibility allows the colony of social insects to be robust and to maintain its life against considerable disturbances.

The dynamism of the social insect population is a result of the different actions and interactions of individual insects with each other, as well as with their environment. The interactions are executed via multitude of various chemical and/or physical signals. The final product of different actions and interactions represents the behaviour of a social insect colony. The examples of such interactive behaviour are dancing of bees during the food procurement, ants' pheromone secretion, and performance of specific acts, which signal the other insects to start the same actions. These communication systems between individual insects contribute to the formation of the "collective intelligence" of the social insect colonies. In spite of the existence of a large number of different social insect species, and variation in their behavioural patterns, it is possible to describe individual insects as species capable of performing a variety of complex tasks. The best example is the collection and processing of nectar, the practice of which is highly organized[5, 34-37].

Each bee decides to reach the nectar source by following a nest mate who has already discovered a patch of flowers. Each hive has a so-called dance floor area in which the bees which have discovered nectar sources dance, in that way trying to convince their nest mates to follow them. If a bee decides to leave the hive to get nectar, she follows one of the dancer bees to one of the nectar areas. Upon arrival, the foraging bee takes a load of nectar and returns to the hive relinquishing the nectar to a food storer bee[5].

After she relinquishes the food, the bee can (a) abandon the food source and become again an uncommitted follower, (b) continue to forage at the food source without recruiting the nest mates, or (c) dance and thus recruit the nest mates before returning to the food source. The bee opts for one of the above alternatives with a certain probability. Within the dance area, the dancer bees "advertise" different food areas. The mechanisms by which the bee decides to follow a specific dancer are not well understood, but it is considered that "the recruitment among bees is always a function of the quality of the food source". The artificial bee colony behaves partially alike, and partially different from bee colonies in nature. Within the Bee Colony Optimization Metaheuristic (BCO), agents that we call artificial bees collaborate in order to solve difficult combinatorial optimization problem. All artificial bees are located in the hive at the beginning of the search process. During the search process, artificial bees communicate directly. Each artificial bee makes a series of local moves, and in this way incrementally constructs a solution of the problem. Bees add solution components to the current partial solution until they create one or more feasible solutions. The search process is composed of iterations. Flying through the space, our artificial bees perform forward pass or backward pass. During forward pass, bees create various partial solutions. They do this via a combination of individual exploration and collective experience from the past. After that, they perform backward pass, i.e. they return to the hive. In the hive, all bees participate in a decision-making process. We assume that every bee can obtain

the information about solutions' quality generated by all other bees. In this way, bees exchange information about quality of the partial solutions created. Bees compare all generated partial solutions. Based on the quality of the partial solutions generated, every bee decides whether to abandon the created partial solution and become again an uncommitted follower, continue to expand the same partial solution without recruiting the nest mates, or dance and thus recruit the nest mates before returning to the created partial solution. Depending on the quality of the partial solutions generated, every bee possesses certain level of loyalty to the path leading to the previously discovered partial solution. During the second forward pass, bees expand previously-created partial solutions, and after that perform again the backward pass and return to the hive. In the hive bees again participate in a decision-making process, perform third forward pass, etc. The iteration ends when one or more feasible solutions are created [5, 34-36, 39-40]. The algorithm parameters whose values need to be set prior the algorithm execution are as follows:

nPop- The number of bees in the hive

nMove- The number of constructive moves during one forward pass

In the beginning of the search, all the bees are in the hive. The following is the pseudo code of the BCO algorithm [5]:

1. Initialization: every bee is set to an empty solution;
2. For every bee, Do the forward pass:
 - a) Set $k = 1$; //counter for constructive moves in the forward pass;
 - b) Evaluate all possible constructive moves;
 - c) According to evaluation, choose one move, using the roulette wheel;
 - d) $k = k + 1$; If $k \leq nMove$ Go To step b.
3. All bees are back to the hive; // backward pass starts;
4. Sort the bees by their objective function value;
5. Every bee decides randomly whether to continue its own exploration and become a recruiter, or to become a follower (bees with higher objective function value have greater chance to continue their own exploration);
6. For every follower, choose a new solution from recruiters by the roulette wheel;
7. If the stopping condition is not met Go To step 2;
8. Output the best result.

The stopping condition could be the maximum number of forward/backward passes or the maximum number of forward/backward passes, without improving the objective function [5, 36-40]. In the next chapter, we are trying to apply the BCO algorithm into the optimal DG placement and sizing problem.

4. Applying BCO Algorithm to the Optimal DG Placement and Sizing Problem

In this chapter, the issue of optimal distributed generation

sources allocation for sample 33 nodes IEEE net work will be solved by the BCO based on assumptions that are to be discussed more, and the concepts which are raised in the chapter 3, and the considered objective function.

The Pseudocode of the solving program which is written in MATLAB is as follows:

1. Start: get the network information.
 2. Perform load-flow and save network data.
 3. Determine the number of bees (*nPop*), the number of constructive moves in each forward pass (*nMove*), and the maximum number of iterations, and determine the number of installable DGs.
 4. Generate initial population.
 5. Forward pass:
 - a. set $k=1$
 - b. Choose one of the constructive moves by means of random Switch.
 - c. $k=k+1$, if $k \leq nMove$ then go to b
 6. Return all the bees to the hive (Backward pass).
 7. Sort the bees (selected solutions) based on their objective function value and save the best result.
- Based on the objective function value, each bee decides to leave its solution and to follow another bee, develops its solution without recruiting other nest mates, and or recruit other nest mates and develop its solution with them.
8. For each of the follower bees, allocate a bee to be followed, using roulette wheel. (A bee with the higher objective function value has higher chance to be followed)
 9. Check the stopping condition (maximum iteration), if it is not met, go to 5.
 10. Output: the best solution; End.

5. Numerical Studies and Results

Before Viewing the results, consider the following assumptions: In the bus connected to the main power (Slack bus), one couldn't install any DG, and this problem could be solved for any number of authorized distributed generators, but the authors solved the problem for 5, 3, and 1 DGs. they also assume that the minimum available DG capacity is 500 kVA, maximum available DG capacity is 3500 kVA, and in this range, the DG capacity is chosen by the program as float. These sources are also used in unit power factor, exclusively active power production.

The solving algorithm is flexible in such a manner that any network data could be easily input, and the parameters such as DG number and power range, number of bees and iterations could be changed.

In this example, the basic voltage has been considered 10.5 kV and the basic power was 1 MVA. The number of bees was 100, and the number of Iterations has been considered 200. Also the number of constructive moves in each forward pass was assumed 1 which has two components that are selected randomly:

- a). DG location changing
- b). DG power changing

Also in objective function, the value of w_1 is 1, and w_2 is 4.

The results can be seen in the following tables and figures.

In figures 1, 2 and 3 The horizontal axis shows the number of the iteration times of searching in once run of the program.

In the first graph, the vertical axis shows the amount of the main cost function. In the second graph the occupied capacity amount of lines is shown and in the third graph we see the losses amount of lines.

Table 1. Literature Review

Author and Reference Number	Optimization Method
Borges & Falcao[6] Dan Zhu[7] Wang & Nehrir[8] Gozel & Hokaoglu[9]	Analytical Methods
Keane[11]	Linear Programming
Kashem[9] El-Khattam[10]	Nonlinear Programming
Rau & Wan[10] Chiradeja[8]	Methods based on Load flow
Harrison & Wallace[11]	Optimal Powerflow
Popovic & Greatbanks[12] Greatbanks & Popovic[13]	Sensitivity Analysis
Alemi & gharepetian & abedi[4]	Sensitivity Coefficients Analysis
Tautiva & Cadena[7]	Heuristic Method
Khales & haghifam & lesani[2]	Dynamic Programming
Celli & Ghiani[14] Haghifam & Falaghi[15] Celli & Pillo[16] Borges & Falcao[16] Teng[17] Kuri & Redfern[18] Tang[19]	Genetic Algorithm
Carpinelli & Celli[20]	Genetic Algorithm with Multi-Purpose Planning
Gandomkar[21]	Genetic Algorithm and Simulated Annealing
Cano[22]	Fuzzy Logic
Kim & Lee[23]	Fuzzy Logic combined with Genetic Algorithm
Katic & Skrlec[13]	Enumeration
Rios & Rubio[24]	Optimization with Successive Repetition
Hadian & haghifam & afrakhte[3]	NSGA-II
Akhavan & golkar & haghifam[1]	CPSO
Nara & Hayashi[25]	Tabu Search
Haghifam & Falaghi[12]	ACO

Table 2. Initial conditions (network without DG)

IC	PLoss	FI	FL	Cost Function
35.8273(p.u.)	0.1544(p.u.)	0	0	5

Table 3. The results of the program running for installation of 5 DGs, using 100 bees, and 200 iterations

Bus Number	DG Capacity (p.u.)	IC (p.u.)	PLoss (p.u.)	FI	FL	Cost Function
1	1.39					
24	0.66					
14	0.52	20.78	0.0072	0.4197	0.9531	0.7678
7	0.73					
30	0.74					

Table 4. The results of the program running for installation of 3 DGs, using 100 bees, and 200 iterations

Bus Number	DG Capacity (p.u.)	IC (p.u.)	PLoss (p.u.)	FI	FL	Cost Function
29	1.0645					
13	0.7322	21.89	0.013	0.3890	0.9104	0.9694
23	0.9823					

Table 5. The results of the program running for installation of 1 DG, using 100 bees, and 200 iterations

Bus Number	DG Capacity (p.u.)	IC (p.u.)	PLoss (p.u.)	FI	FL	Cost Function
5	2.3970	27.7295	0.060	0.226	0.611	2.3275

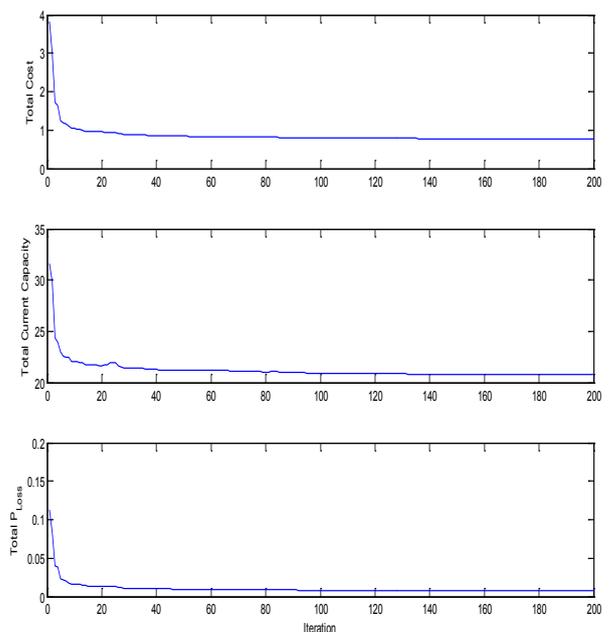


Figure 1. The results of the program running for installation of 5 DGs, using 100 bees, and 200 iterations

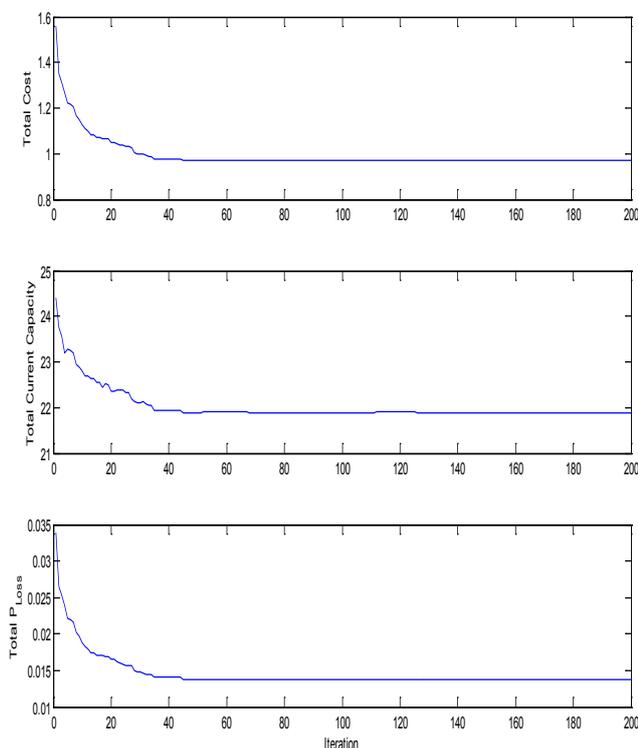


Figure 2. The results of the program running for installation of 3 DGs, using 100 bees, and 200 iterations

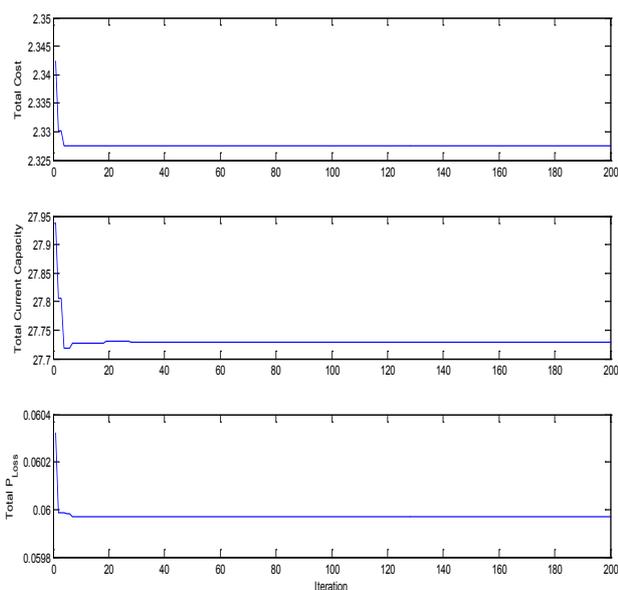


Figure 3. The results of the program running for installation of 1 DG, using 100 bees, and 200 iterations

6. Conclusions

In this research, the problem of determining the optimal position, numbers, and capacity of distributed generators, was studied. Initially the background of this problem was reviewed, and the necessity to do further research with different objectives and attitudes about this issue was explained. Regarding the development process in Islamic Re-

public of Iran and consequently the restructuring of industry and electricity market, a careful study on optimal DG allocation with different aim and methods is essential, in order to prevent waste of capital and other considerations. Due to the high rate of distribution losses in Islamic Republic of Iran, (which is over 20%), authors chose this index along with the amount of free line's capacity index as their optimization objectives. Then the forward-backward sweep power flow was introduced and coded. The primary objective in this paper was presenting Bee Colony Optimization (BCO) algorithm as a new and efficient method to solve optimization problems, and especially the problem of optimal DG allocation.

BCO results show that this method has a good convergence, and each time the program was run, a same output was received.

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