

Research on Precision Process in MCF Polishing

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Abstract Our research group has demonstrated experimentally that the polishing effect using our developed intelligent fluid, magnetic compound fluid (MCF), is greater than that using previously developed intelligent fluids, i.e., magnetic fluid (MF) and magneto-rheological fluid (MRF). Prof. Shimada succeeded in float polishing with a large clearance utilizing a newly developed magnetic responsive fluid, MCF, which was improved by the addition of α -cellulose, thereby achieving a clearance as great as 8mm. He also clarified the mechanism of the new polishing technique. A comparison of the MCF polishing effect with those of techniques using the ordinary magnetic responsive fluids, MF and MRF, showed the polishing effect of MCF to be greater than those of MF and MRF. The MCF polishing technique is applicable to many types of polishing, widening the variety of the uses of magnetic float polishing (MFP). In this study, we proposed a new process method for the MCF polishing.

Keywords MCF (Magnetic Compound Fluid), Polishing, Abrasion liquid, Surface roughness

In order to further develop nano- or micro-technology, nano- or micro-polishing techniques are needed to polish or grind the material surfaces of nano- or micro-devices on a nm-order. In response to this need, in our laboratory, we have researched MCF (Magnetic Compound Fluid) polishing for years. MCF polishing is a kind of smart fluid polish. An alumina abrasive particle of $3.0[\mu\text{m}]$ was included in the MCF abrasion liquid (Table 1) used for conventional experiments. However, undulation sometimes occurred on the surface of the polished samples (aluminium, acrylic resin etc.). This was because the abrasive particle was relatively large, which made it glide on the polished sample surface. As a result, the polishing process did not work well. Therefore, I proposed a new method of MCF polishing. The new method uses a smaller abrasive particle (alumina particle of $0.06[\mu\text{m}]$) to accomplish MCF polishing (Table 2, Table 3). Using this method, we expected to be able to polish away the smaller irregularities. In addition, we assumed that undulation on the sample surface would disappear after MCF polishing.

Accordingly, some proof experiments were performed in our lab. Under the conventional experimental conditions, it was difficult to achieve a surface roughness R_a smaller than $0.05[\mu\text{m}]$. Conversely, after completing the MCF polishing process (Fig.1), the surface roughness R_a of samples was smaller (R_a was around $0.03[\mu\text{m}]$ and minimum R_a was $0.013[\mu\text{m}]$). Therefore, it may be said that the newly

proposed experimental method provided sufficient abrasive effect. Through these experiments, I am convinced that using MCF abrasion liquid with smaller alumina abrasive particles ($0.06[\mu\text{m}]$) for MCF polishing is a superior method. It creates polished sample surfaces that are sleek, like a mirror.

Furthermore, when you see the appearance of the polished samples, there is neither undulation nor irregularities on the sample surface, so that it appears mirror-like. Thus, I can report that the complete MCF polishing technology has arrived at the practical level and will be applied widely in the industrial world.

Table 1. Polishing Liquid 1 (PL1)

Ingredients of the polishing liquid	Weight ratio (g)
Magnetic fluid (MSG60)	19.6
Carbonyl Fe fine particles (HQ, 1 μm)	15.2
Polishing particles (alumina 3 μm)	10
α -cellulose	3.2
Kerosene	2

Table 2. Polishing Liquid 2 (PL2)

Ingredients of the polishing liquid	Weight ratio(g)
Magnetic fluid (MSG60)	19.6
Carbonyl Fe fine particles (HQ, 1 μm)	15.2
Polishing particles (alumina 0.06 μm)	2.5
α -cellulose	3.2
Kerosene	2

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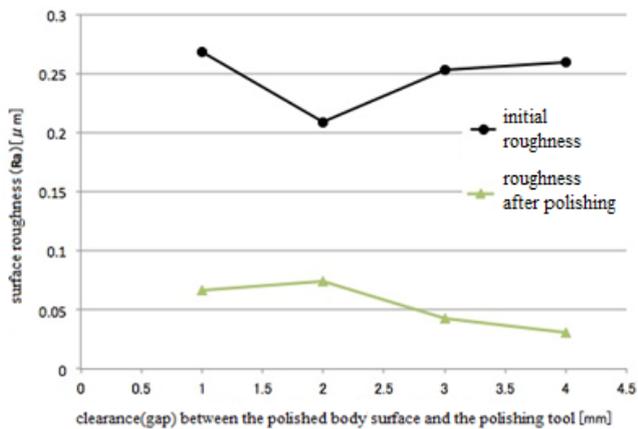
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Table 3. New experiment condition

Ingredients of the polishing liquid	PL1 and PL2
Clearance(gap) between the polished body's surface and the polishing tool	1,2,3,4 (mm)
Rotary speed of the polishing tool	515 (rpm)
Polishing time	30 (min) with PL1 and 30 (min) with PL2
Permanent magnet used	Neodymium magnet
Polished body material	Aluminum (thickness 1mm)
Polished body motion	Parallel motion

**Figure 1.** Results of new experiment condition (polished material was an aluminum plate)

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