

A Novel Finite Element Method for Analysing the Confinement Effect in Concrete-Filled Steel Tubes

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Abstract Most theoretical models of non-uniform concrete confinement use empirical equations and thus are applicable only to limited ranges of geometric and material parameters. In light of such shortcomings, a novel finite element (FE) method is proposed to explicitly compute the non-uniform lateral confining stresses in the concrete section. To determine the lateral stresses, the lateral strains are divided into two components: an elastic component and an inelastic component, and a 2-dimensional FE analysis of the concrete section with the inelastic lateral strains taken as initial strains is carried out. Since the lateral stresses and inelastic lateral strains are inter-related, an iterative process of evaluating the lateral stresses from the inelastic lateral strains by FE analysis and then evaluating the inelastic lateral strains from the lateral stresses by a lateral strain model is employed until convergent results are obtained. This FE method is herein applied to square concrete-filled steel tube columns.

Keywords Concrete-filled steel tube (CFST), Confinement effect, Finite element analysis

1. Introduction

A concrete-filled steel tube (CFST) has higher strength and ductility than traditional reinforced concrete, owing to the confinement effect therein. It has become widely adopted in bridges, e.g. Hejiang Bosiden Bridge and Guangzhou Yajisha Bridge, and tall buildings, e.g. Shenzhen KK100. However, the effectiveness of confinement in CFST is dependent on the section shape and loading type. In theory, a circular CFST column under axial loading has uniform confinement over the entire concrete section before any local buckling occurs, whereas a non-circular (rectangular, elliptical or polygonal) CFST column under any loading or a circular CFST under eccentric loading has non-uniform and generally less effective confinement.

Many empirical axial strength and stress-strain models of confined concrete have been developed by incorporating the effects of confinement, whether uniform or non-uniform, in terms of empirical factors dependent on the geometric and material parameters without explicit consideration of the actual distribution of confining stresses [1-7]. In a recent study by Yu et al. [8, 9] on concrete confined by fibre-reinforced polymer (FRP), the finite element (FE) method was employed to analyse the confining stresses. A pivotal step was taken to simulate the interaction between

the laterally expanding concrete and the confining FRP by making solution-dependent adjustments to the dilation angle of the plastic flow potential of the concrete.

To avoid such complicated adjustments, the authors have developed a novel FE model, which allows directly computation of the inelastic components of the lateral strains, from which the confining stresses can be evaluated [10, 11]. This paper presents the key features of the FE model and some numerical results obtained for square CFST.

2. Concrete Modelling

This model simulates the constitutive behaviour of concrete under confinement using the lateral strain-axial strain relation developed by Dong et al. [12], the triaxial failure surface developed by Menétrey and Willam [13] and the axial stress-strain relation of confined concrete developed by Attard and Setunge [14]. Detailed mathematical formulations of the three models are presented in Table 1 for reference.

According to Dong et al. [12], the lateral strains of concrete in the two in-plane directions each comprises of two components, an elastic component and an inelastic component. Based on this postulation, the in-plane principal lateral strains ε_1 and ε_2 in each concrete element can be expressed as $\varepsilon_1 = \varepsilon_1^e + \varepsilon_1^p$ and $\varepsilon_2 = \varepsilon_2^e + \varepsilon_2^p$, in which ε_1^e and ε_2^e are the elastic components, and ε_1^p and ε_2^p are the inelastic components. With the inelastic components taken as initial strains, the constitutive equation of concrete at element level may be expressed as:

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$$\begin{Bmatrix} \sigma_1 \\ \sigma_2 \\ \tau_{12} \end{Bmatrix} = \lambda_c \begin{bmatrix} 1 - \nu_c & \nu_c & 0 \\ \nu_c & 1 - \nu_c & 0 \\ 0 & 0 & \frac{1 - \nu_c}{2} \end{bmatrix} \begin{Bmatrix} \varepsilon_1 - \varepsilon_1^p \\ \varepsilon_2 - \varepsilon_2^p \\ \gamma_{12} \end{Bmatrix} + \lambda_c \nu_c \begin{Bmatrix} \varepsilon_3 \\ \varepsilon_3 \\ 0 \end{Bmatrix} \quad (1a)$$

$$\lambda_c = \frac{E_c}{(1 + \nu_c)(1 - 2\nu_c)} \quad (1b)$$

where E_c and ν_c are the Young's modulus and Poisson's ratio of the concrete. The inelastic components in Eq. (1a) are

dependent on the axial strain in the longitudinal direction ε_3 , the lateral confining stresses σ_1 and σ_2 , and the concrete cylinder strength f_c , as given by:

$$\varepsilon_1^p = -19.1(\varepsilon_3 - \varepsilon_{3,1}^{lim})^{1.5} \left\{ 0.1 + 0.9 \left[\exp \left(-5.3 \left(\frac{\sigma_1}{f_c} \right)^{1.1} \right) \right] \right\} \quad (2a)$$

$$\varepsilon_2^p = -19.1(\varepsilon_3 - \varepsilon_{3,2}^{lim})^{1.5} \left\{ 0.1 + 0.9 \left[\exp \left(-5.3 \left(\frac{\sigma_2}{f_c} \right)^{1.1} \right) \right] \right\} \quad (2b)$$

The expressions of $\varepsilon_{3,1}^{lim}$ and $\varepsilon_{3,2}^{lim}$ can be found in Table 1.

Table 1. Adopted concrete models

Authors	Model Expressions
Dong et al. [12]	$\varepsilon_1^p = -19.1(\varepsilon_3 - \varepsilon_{3,1}^{lim})^{1.5} \left\{ 0.1 + 0.9 \left[\exp \left(-5.3 \left(\frac{\sigma_1}{f_c} \right)^{1.1} \right) \right] \right\}$ $\varepsilon_2^p = -19.1(\varepsilon_3 - \varepsilon_{3,2}^{lim})^{1.5} \left\{ 0.1 + 0.9 \left[\exp \left(-5.3 \left(\frac{\sigma_2}{f_c} \right)^{1.1} \right) \right] \right\}$ <p>where:</p> $\varepsilon_{3,1}^{lim} = \varepsilon_{co} (0.44 + 0.0021f_c - 0.00001f_c^2) \left[1 + 30 \exp(-0.013f_c) \frac{\sigma_1}{f_c} \right]$ $\varepsilon_{3,2}^{lim} = \varepsilon_{co} (0.44 + 0.0021f_c - 0.00001f_c^2) \left[1 + 30 \exp(-0.013f_c) \frac{\sigma_2}{f_c} \right]$
Menétrey and Willam [13]	$F(\xi, \rho, \theta) = \left(\sqrt{1.5} \frac{\rho}{f_c} \right)^2 + m \left[\frac{\rho}{\sqrt{6}f_c} r(\theta, e) + \frac{\xi}{\sqrt{3}f_c} \right] - c = 0$ <p>where:</p> $\xi = \frac{I_1}{\sqrt{3}}; \quad I_1 = \sigma_1 + \sigma_2 + \sigma_3$ $\rho = \sqrt{2J_2}; \quad J_2 = \frac{1}{6} [(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2]$ $\theta = \frac{1}{3} \cos^{-1} \left(\frac{3\sqrt{3}J_3}{2J_2^{3/2}} \right); \quad J_3 = (\sigma_1 - \frac{I_1}{3})(\sigma_2 - \frac{I_1}{3})(\sigma_3 - \frac{I_1}{3})$ $m = 3 \frac{f_c^2 - f_t^2}{f_c f_t} \cdot \frac{e}{e + 1}$ $r(\theta, e) = \frac{4(1 - e^2)\cos^2\theta + (2e - 1)^2}{2(1 - e^2)\cos\theta + (2e - 1)[4(1 - e^2)\cos^2\theta + 5e^2 - 4e]^{1/2}}$
Attard and Setunge [14]	<p>Descending branch:</p> $\alpha_1 = \left(\frac{\varepsilon_{2i} - \varepsilon_i}{\varepsilon_{co}} \right) \left(\frac{\varepsilon_{2i} E_i}{f_{cc} - f_i} - \frac{4\varepsilon_i E_{2i}}{f_{cc} - f_{2i}} \right)$ $\alpha_2 = (\varepsilon_{2i} - \varepsilon_i) \left(\frac{E_i}{f_{cc} - f_i} - \frac{4E_{2i}}{f_{cc} - f_{2i}} \right)$ $\alpha_3 = \alpha_1 - 2$ $\alpha_4 = \alpha_2 + 1$ $\frac{f_i}{f_{cc}} = \frac{\frac{f_{ic}}{f_c} - 1}{5.06 \left(\frac{f_i}{f_c} \right)^{0.57} + 1} + 1$ $\frac{f_{2i}}{f_{cc}} = \frac{\frac{f_{2ic}}{f_c} - 1}{6.35 \left(\frac{f_i}{f_c} \right)^{0.62} + 1} + 1$ $\frac{\varepsilon_i}{\varepsilon_{cc}} = \frac{\frac{f_{ic}}{f_c} - 2}{1.12 \left(\frac{f_i}{f_c} \right)^{0.26} + 1} + 2$ $\varepsilon_{2i} = 2\varepsilon_i - \varepsilon_{cc}$ $\frac{f_{2ic}}{f_c} = 1.45 - 0.25 \ln(f_c)$ <p>Ascending branch:</p> $\alpha_1 = \frac{E_{ii} \varepsilon_{co}}{f_c}$ $\alpha_2 = \frac{(\alpha_1 - 1)^2}{\frac{E_{ii}}{E_c} \left(1 - \frac{f_{pl}}{f_c} \right)} + \frac{\alpha_1^2 \left(1 - \frac{E_{ii}}{E_c} \right)}{\left(\frac{E_{ii}}{E_c} \right)^2 \left[\frac{f_{pl}}{f_c} - \left(\frac{f_{pl}}{f_c} \right)^2 \right]} - 1$ $\alpha_3 = \alpha_1 - 2$ $\alpha_4 = \alpha_2 + 1$

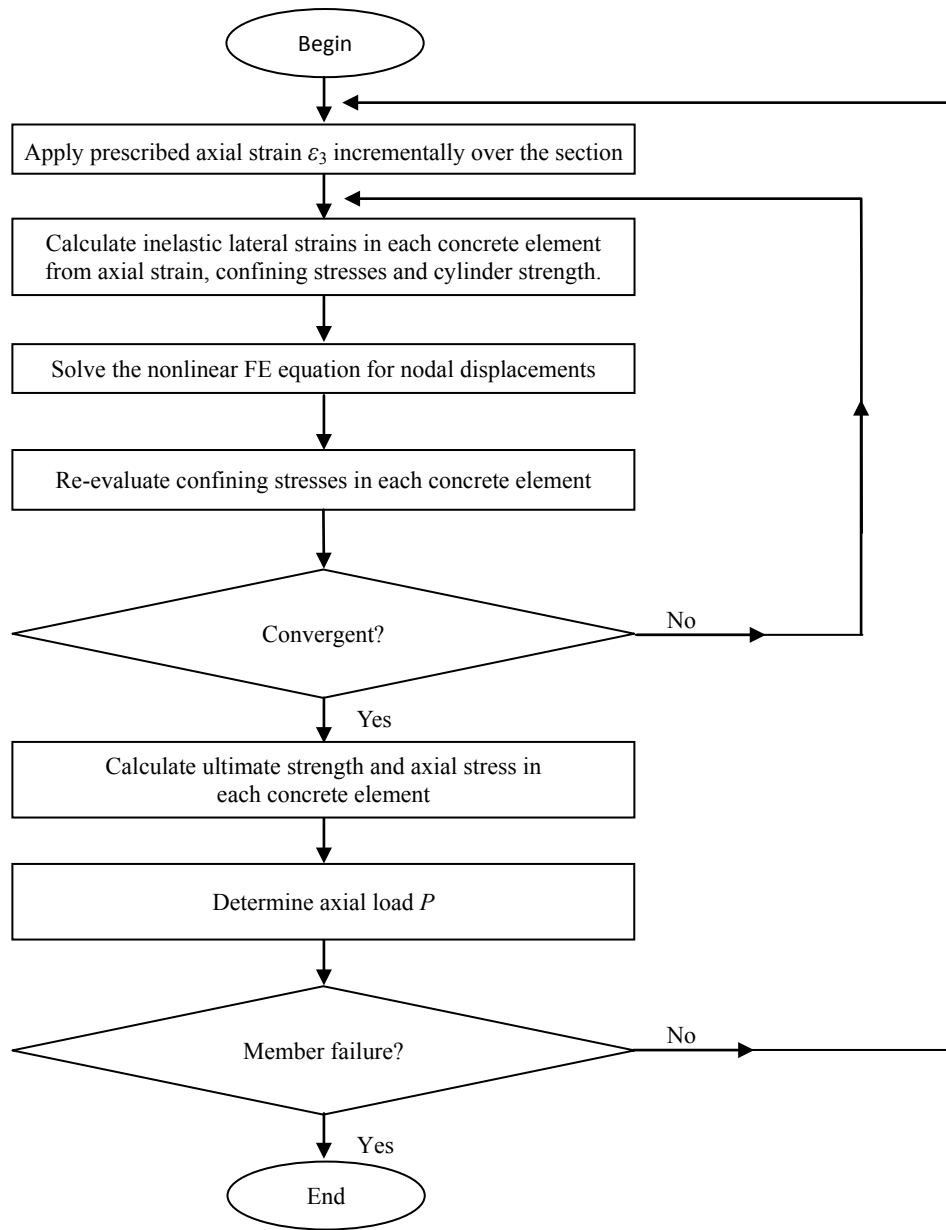


Figure 1. Procedures for the FE analysis

Triangular three-noded (T3) elements are used. Hence, the axial strain ε_3 at the centroid of the T3 element is used in Eqs. 1 and 2. The stiffness matrix equation of the concrete elements in the global coordinate system is derived as:

$$F = \Delta \{B^T A^T C A B u - B^T A^T C \varepsilon_{1,2}^p + B^T (\lambda v_c \varepsilon_3)\} \quad (3)$$

in which Δ is the area of the T3 element; B is the strain-displacement matrix of the T3 element; A is the strain transformation matrix converting the global lateral strain vector $\{\varepsilon_x \ \varepsilon_y \ \gamma_{xy}\}^T$ to the local principal strain vector $\{\varepsilon_1 \ \varepsilon_2 \ \gamma_{12}\}^T$; u is the nodal displacement vector $\{u_1 \ v_1 \ u_2 \ v_2 \ u_3 \ v_3\}^T$ for the T3 element; $\varepsilon_{1,2}^p$ is the local inelastic strain vector $\{\varepsilon_1^p \ \varepsilon_2^p \ 0\}^T$; ε_3 is the axial strain vector $\{\varepsilon_3 \ \varepsilon_3 \ 0\}^T$ in both local and global coordinate systems; and C is the constitutive matrix of the concrete.

The triaxial failure surface developed by Menétrey and Willam [13] is given by:

$$F(\xi, \rho, \theta) = \left(\sqrt{1.5} \frac{\rho}{f_c}\right)^2 + m \left[\frac{\rho}{\sqrt{6} f_c} r(\theta, e) + \frac{\xi}{\sqrt{3} f_c}\right] - c = 0 \quad (4)$$

where ξ is the hydrostatic length; ρ is deviatoric length; θ is the Lode angle; m is the friction parameter; e is the out-of-roundness parameter; and c is the cohesion parameter. The uniaxial tensile strength f_t is assumed as $-0.1f_c$. When Eq. (4) is only describing the failure surface, c should be equal to 1. The value of e can be derived by putting $\sigma_1 = 0$ and $\sigma_2 = \sigma_3 = 1.5f_c^{0.925}$ into Eq. (4):

$$e = \frac{44.55f_c^{-0.075} + 6.75f_c^{-0.15} - 3}{89.1f_c^{-0.075} - 6.75f_c^{-0.15} + 3} \quad (5)$$

as per the suggestion by Papanikolaou and Kappos [15] that the biaxial-to-uniaxial compressive strength ratio of concrete should be given by $1.5f_c^{-0.075}$. As far as the failure surface is concerned, the compressive strength of confined concrete f_{cc} is equivalent to σ_3 in Eq. (4) and can be calculated from the lateral confining stresses σ_1 and σ_2 at each iteration step.

The relation between the axial strain ε_3 and the axial stress σ_3 (different from σ_3 in Eq. (4)) of each concrete element may be determined by Attard and Setunge's model [14]. The mathematical expression of this model is given by:

$$\frac{\sigma_3}{f_{cc}} = \frac{a_1 \left(\frac{\varepsilon_3}{\varepsilon_{cc}} \right) + a_2 \left(\frac{\varepsilon_3}{\varepsilon_{cc}} \right)^2}{1 + a_3 \left(\frac{\varepsilon_3}{\varepsilon_{cc}} \right) + a_4 \left(\frac{\varepsilon_3}{\varepsilon_{cc}} \right)^2} \quad (6)$$

where ε_{cc} is axial strain at peak stress corresponding to f_{cc} , and a_1 , a_2 , a_3 and a_4 are coefficients governing the shape of the stress-strain curve. It should be stressed that Attard and Setunge's original mathematical expressions for f_{cc} is only applicable to the cases in which the confining stresses along the two principal axes have the same magnitude, i.e. $\sigma_1 = \sigma_2 = f_r$, and is replaced by Menétrey and Willam's triaxial failure surface since the latter is more suitable for anisotropic cases. f_r is also used to determine other parameters in Attard and Setunge's model. When σ_1 and σ_2 are not equal to each other, f_r is assumed to be the minimum of σ_1 and σ_2 , as a compromised approach.

3. Nonlinear FE Analysis of Square CFST

The analysis procedure for axially loaded square CFST

columns is illustrated in Fig. 1.

The axial strain ε_3 of each concrete is the prescribed input, the inelastic lateral strain vector $\varepsilon_{1,2}^p$ of concrete in Eq. (3) can be determined by Dong et al.'s [12] lateral strain-axial strain relation. Likewise, the plastic strain vectors ε^p and ε_3^p of steel can be determined by von-Mises yield criterion and the associated plastic flow. Subsequently, the global stiffness matrix equation can be assembled as:

$$K \cdot u = F_p \{ \varepsilon_{1,2}^p [\sigma(u), \varepsilon_3], \varepsilon^p \} - F_3(\varepsilon_3, \varepsilon_3^p) \quad (7)$$

where F_p and F_3 are load vectors related to the residual strains (inelastic lateral strains of concrete and plastic strains of steel) and axial strains in the concrete elements and steel elements. In Eq. (7), the residual strain vector on the right hand side is dependent on the nodal displacement vector on the left hand side. An iteration process is adopted to calculate the approximate solutions to Eq. (7) in each loading step. More specifically, a nodal displacement vector u_i can be calculated using the current values of axial strains and confining stresses in Step i :

$$K \cdot u_i = F_p \{ \varepsilon_{1,2}^p [\sigma_i, \varepsilon_3], \varepsilon^p \} - F_3(\varepsilon_3, \varepsilon_3^p) \quad (8)$$

Then the new nodal displacement vector can be used to produce a new stress vector σ'_i , which is used to compute the confining stresses for the $i+1^{\text{th}}$ iteration:

$$\sigma_{i+1} = r \cdot \sigma_i + (1 - r) \cdot \sigma'_i(u_i), \quad (0 < r < 1) \quad (9)$$

where r is the relaxation factor. Normally the value of r is set between 0.3 and 0.7 to maintain the convergence rate during the iteration process.

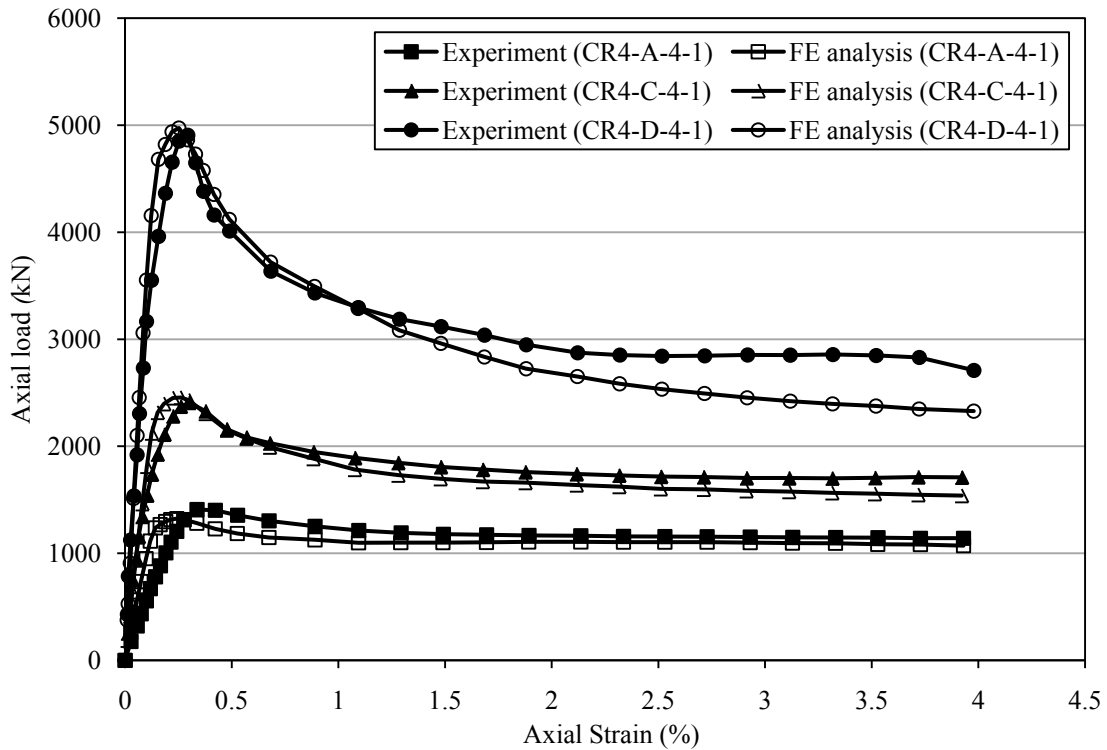


Figure 2. Load-strain curves

After the principal lateral stresses σ_1 and σ_2 of each concrete element are converging to steady values, i.e. their approximate solutions are found, they can be used to evaluate f_{cc} via Men  trety and Willam's triaxial failure surface. With the input of $\varepsilon_3, f_{cc}, f_r = \min\{\sigma_1, \sigma_2\}$, and the use of Attard and Setunge axial stress-strain relation, the axial stress σ_3 of each concrete element can be evaluated. Meanwhile, the axial stress σ_3 of each steel element is determined also by von-Mises yield criterion and the associated plastic flow. The force P can be calculated by integrating σ_3 over the whole CFST section.

If there is flexural behaviour involved other than axial compression, an extra level of iteration involving member analysis should also be added to the procedure.

4. Applications

The FE model is verified against the experimental results of 3 axially loaded square CFST columns from Sakino et al.'s publication [16]. The sectional edge length for the columns CR4-A-4-1, CR4-C-4-1 and CR4-D-4-1 are 148 mm, 215 mm and 323 mm respectively; the steel tubes for all three have yield strength of 262 MPa and thickness of 4.38 mm; the cylinder strengths of concrete are 40.5 MPa for CR4-A-4-1 and 41.1 MPa for the other two. In Fig. 2, the peak loads of CR4-A-4-1, CR4-C-4-1 and CR4-D-4-1 predicted by the FE model are 0.94, 1.02 and 0.98 times their respective experimental results; as far as the residual strength at $\varepsilon_3 = 4.0\%$ is concerned, those multiples will become 0.94, 0.90 and 0.86. Overall, the predictions by the FE model agree quite well with the test results.

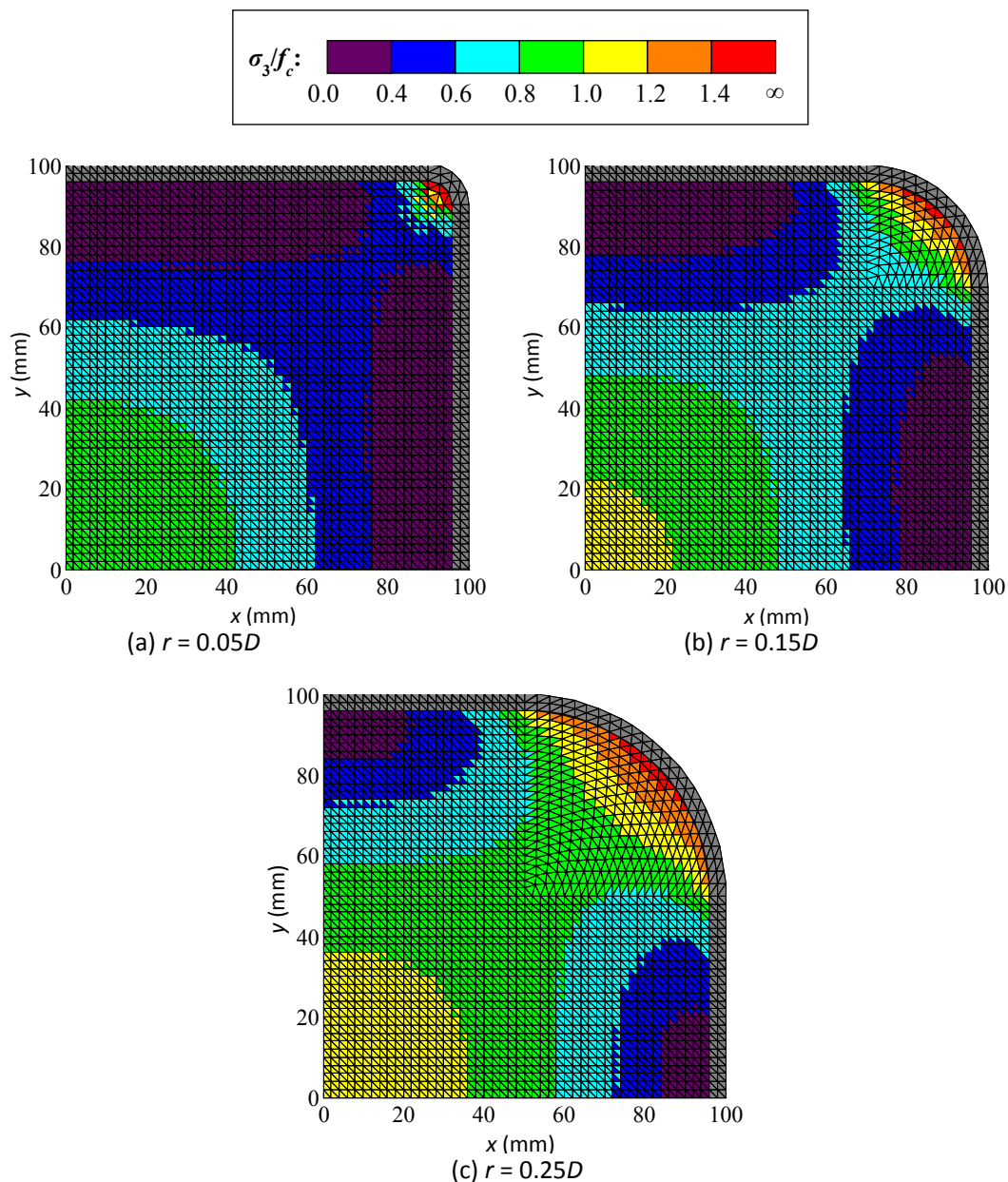


Figure 3. Concrete axial stress contour at $\varepsilon_3 = 4.0\%$

The corner effect is also studied with the help of the FE model. Fig. 3 shows the simulated distributions of axial stress for a series of axially loaded square CFST columns with edge length of 200 mm, tube thickness of 4 mm, S355 steel, Grade 80 concrete and corner radii of 10, 30 and 50 mm. It is discovered that the confinement effect is better at the corners and centre of the section. As the corner radius increases, the effectively confined concrete areas at $\varepsilon_3 = 4.0\%$ will increase, hence the residual strength of the column will be maintained at a higher level.

5. Conclusions

This paper has presented a novel FE method that utilizes Dong et al.'s lateral strain-axial strain model, Men  trety and Willam's triaxial failure surface and Attard and Setunge's axial stress-strain model under confined condition to analyse the passive confinement effect induced by the lateral expansion of concrete within CFST. The use of initial strains in the formulation of the global stiffness matrix equation is the key to compute passive confining stresses in the FE analysis. Owing to this new tool, the load-strain relation and the axial stress contour of CFST can be simulated, thus enabling further exploration on various phenomena in CFST, such as the corner effect.

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